



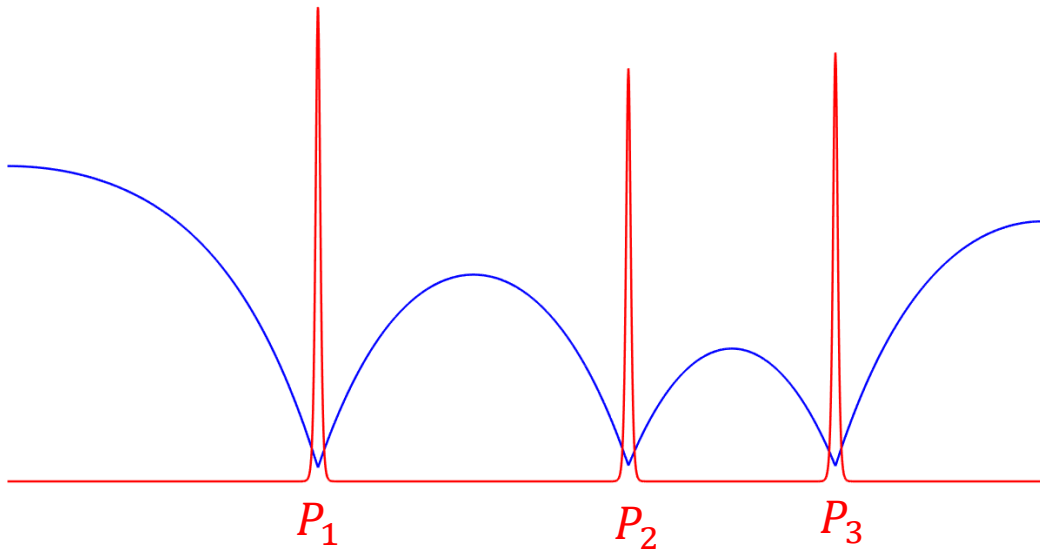
**SIAM DS23 – MT2 – SPATIAL PATTERNS IN NATURE:
AN ENTRY-LEVEL INTRODUCTION TO THEIR EMERGENCE & DYNAMICS**

DYNAMICS OF EXISTING PATTERNS

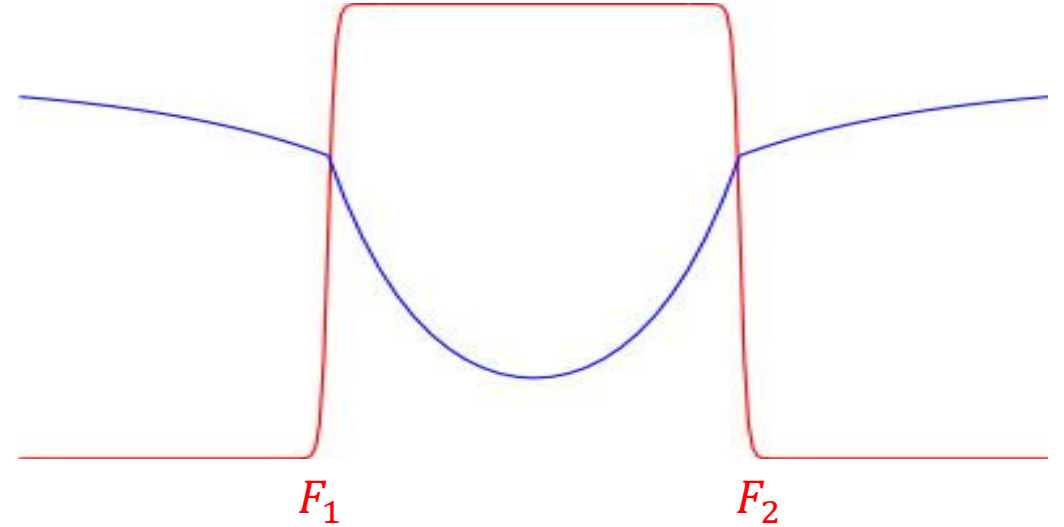
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SIAM DS23, 2023-05-14**

SETTING – pre-existing structures

PULSES



FRONTS



These patterns are fully described by the location of the local structures

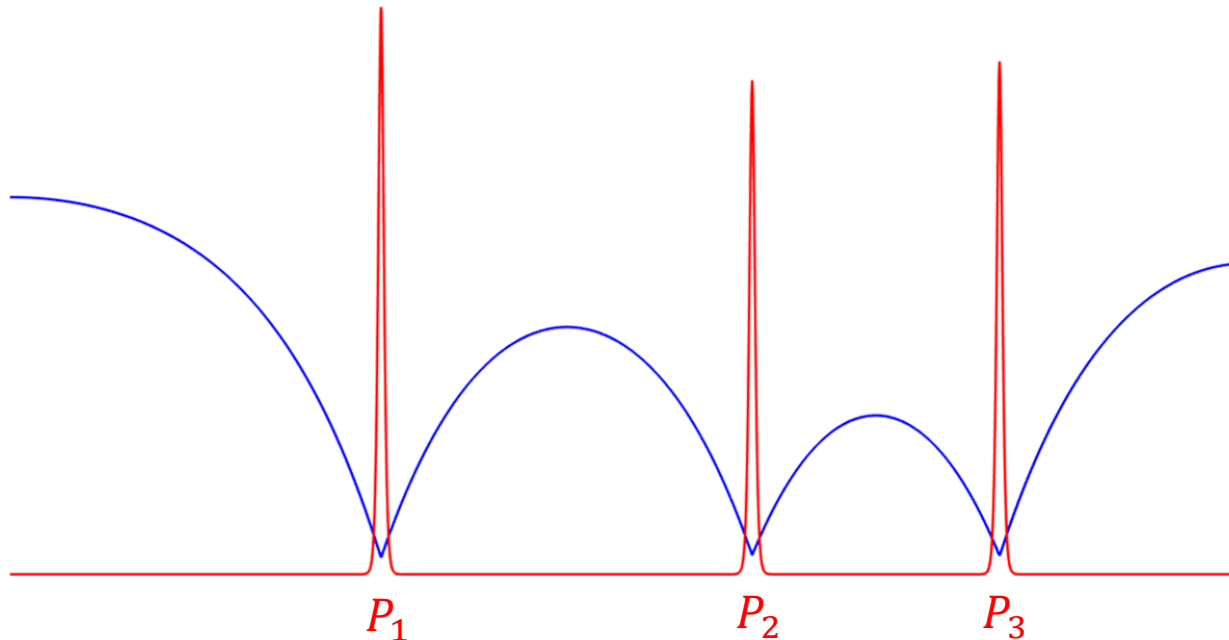
This section: How do they change over time?

Dynamics of patterns

- PDE: infinite-dimensional state space
- Reduction possible because of localised structures

DYNAMICS in two manners:

1. (SLOW) migratory movement of localised structures [Pattern Adaptation]
2. (FAST) structural changes [Pattern Degradation]



1. SLOW pattern adaptation

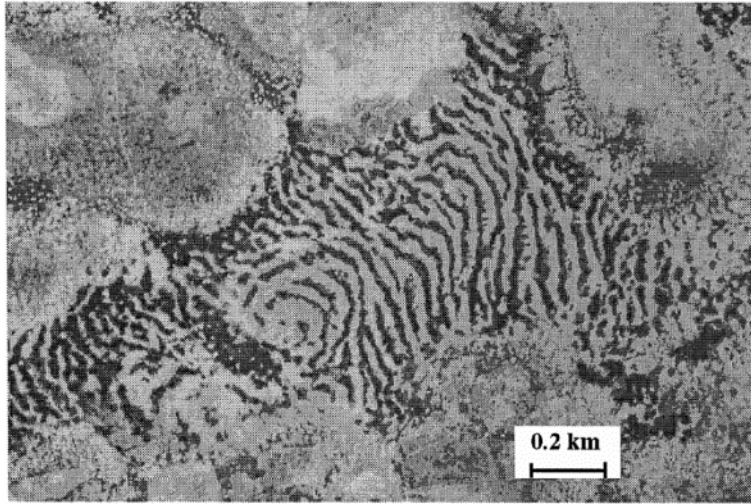


Somaliland, 1948 [Macfadyen, 1950]



Somaliland, 2008

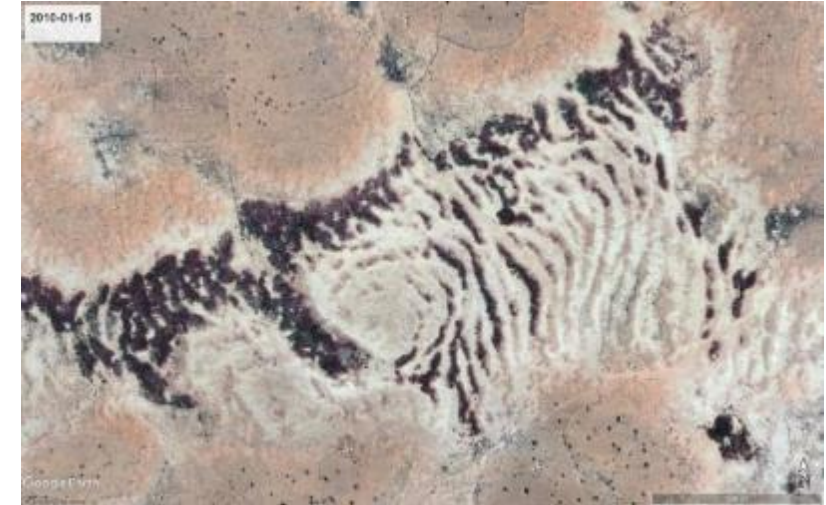
2. FAST Pattern Degradation



Niger, 1950 [Valentin, 1999]



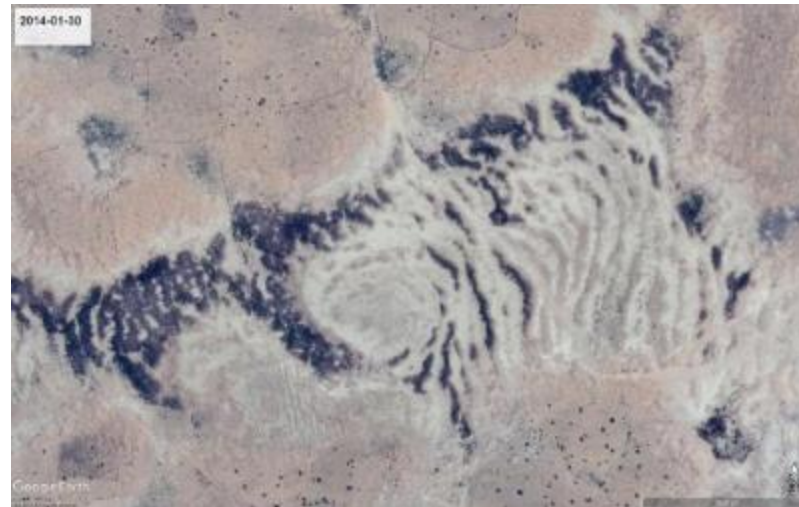
Niger, 2008



Niger, 2010



Niger, 2011



Niger, 2014



Niger, 2016

Example system: dryland ecosystems [reminder]

Extended-Klausmeier model

$$\begin{aligned}w_t &= w_{xx} + (h_x w)_x - w + a - wv^2 \\v_t &= D^2 v_{xx} - mv + wv^2\end{aligned}$$

w : water

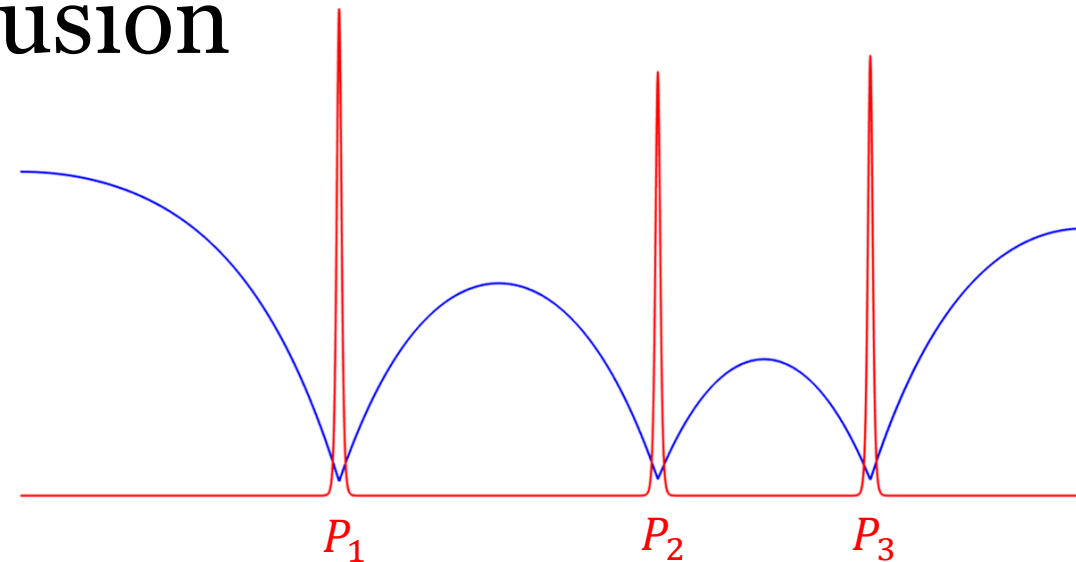
D : ratio of diffusion

v : vegetation

a : rainfall

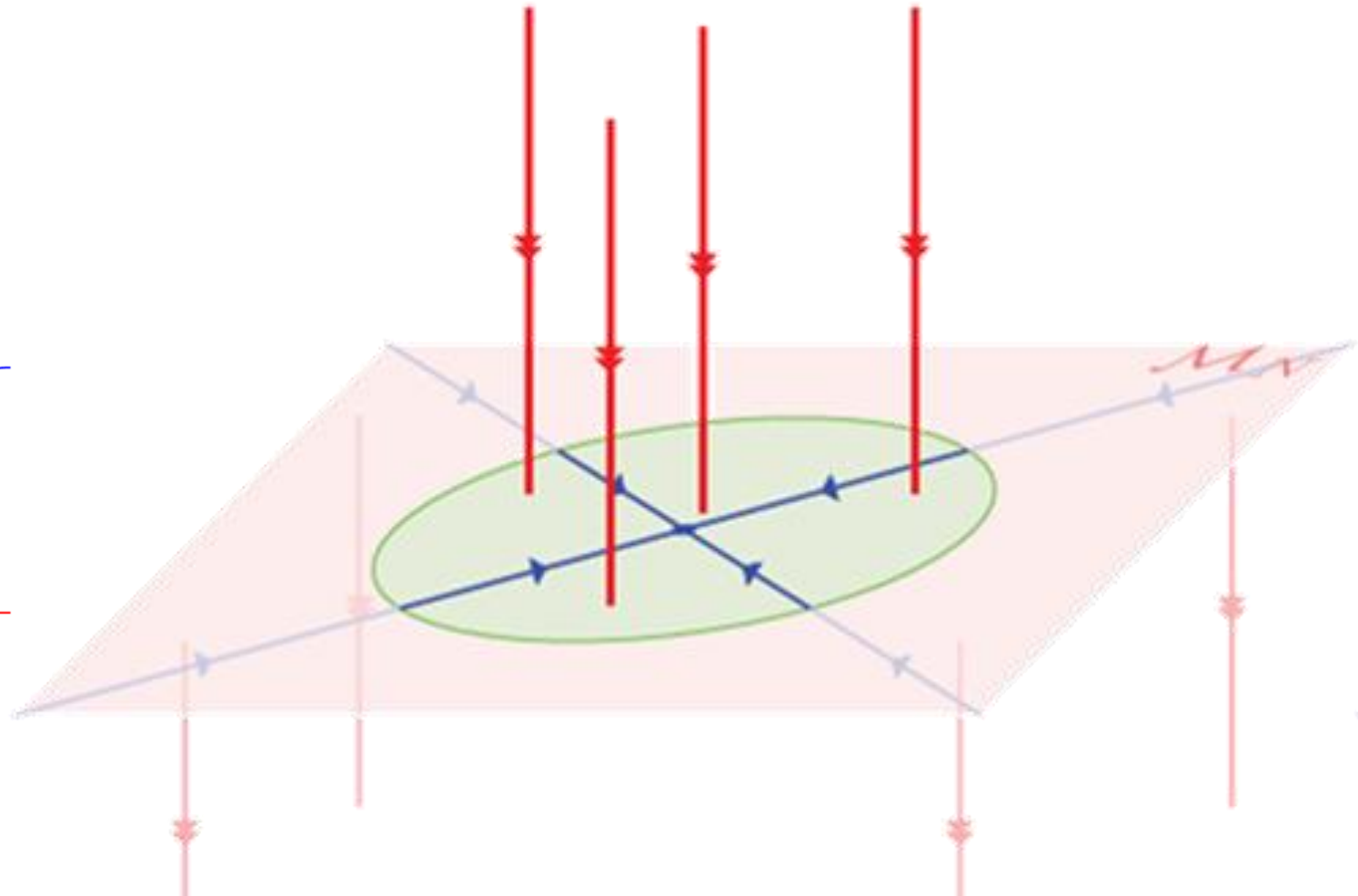
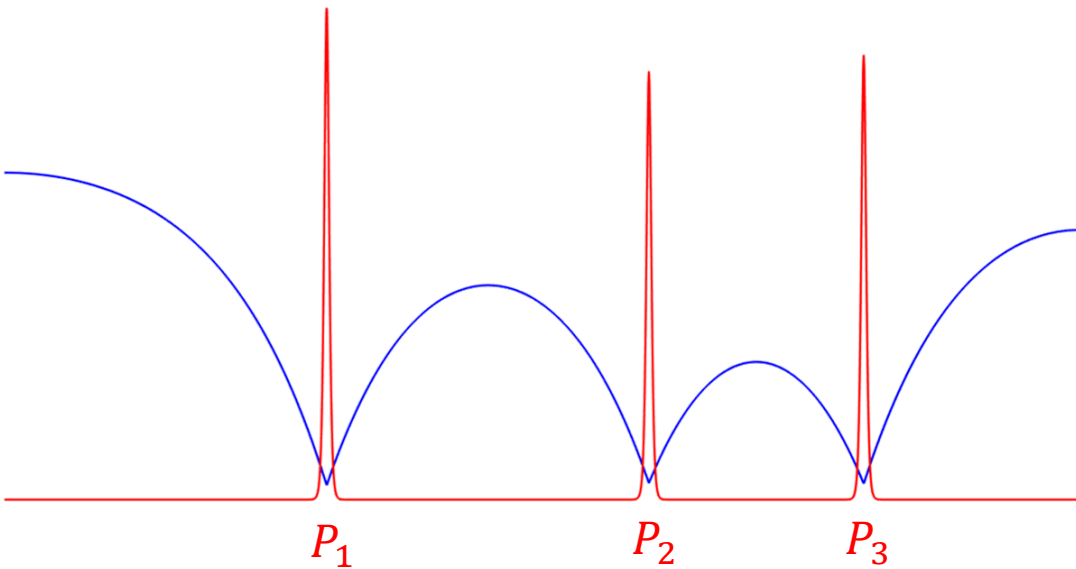
h : height

m : mortality

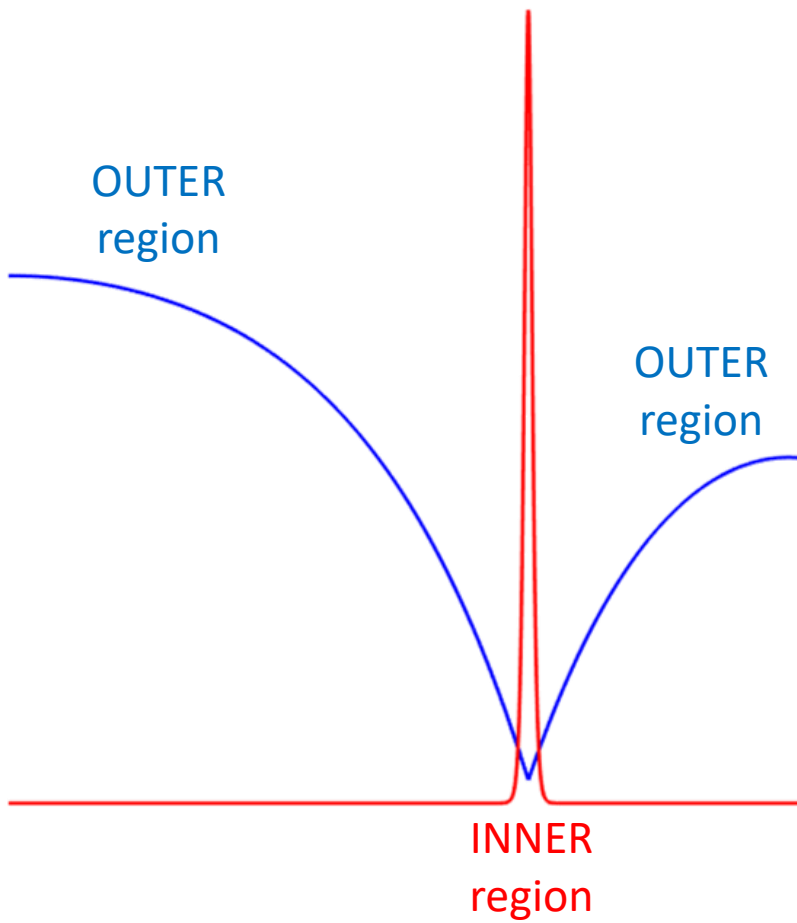


Dynamics of pulses in extended-Klausmeier

1. Pulse-location ODE: describe movement of pulses
2. Stability criterium: test if configuration is feasible



Derivation of pulse-location ODE



$$\begin{aligned}
 w_t &= w_{xx} + (h(\mathbf{x})_x w)_x - w + a(\mathbf{t}) - wv^2 \\
 v_t &= D^2 v_{xx} - mv + wv^2
 \end{aligned}$$

INNER regions:

$$0 = D^2 v_{xx} - mv + wv^2$$

$$\rightarrow v_p(x - P_j(\mathbf{t}))$$

OUTER regions:

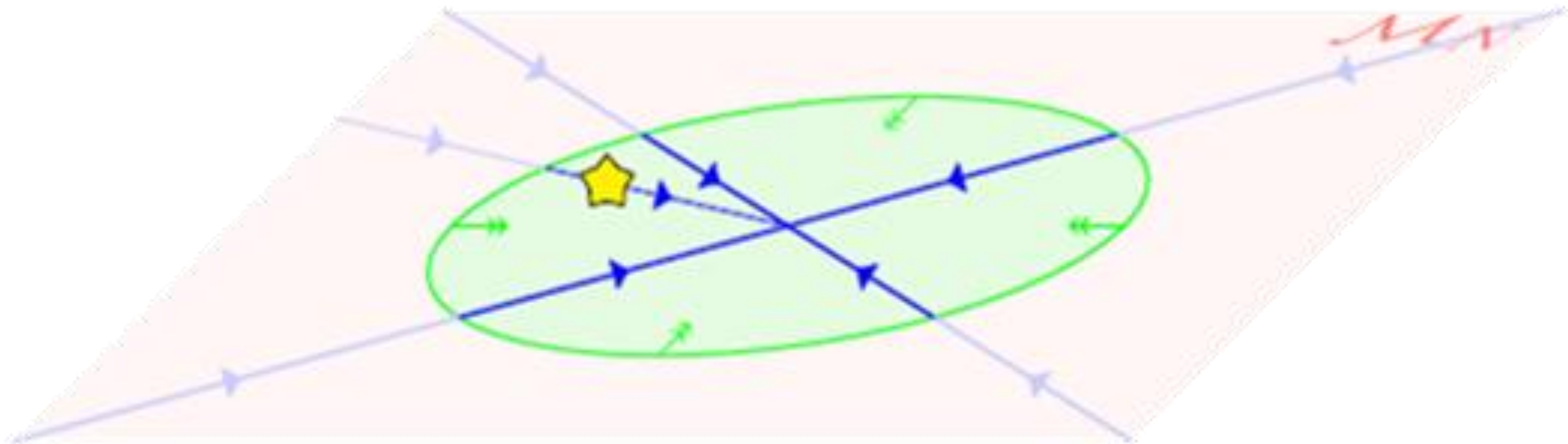
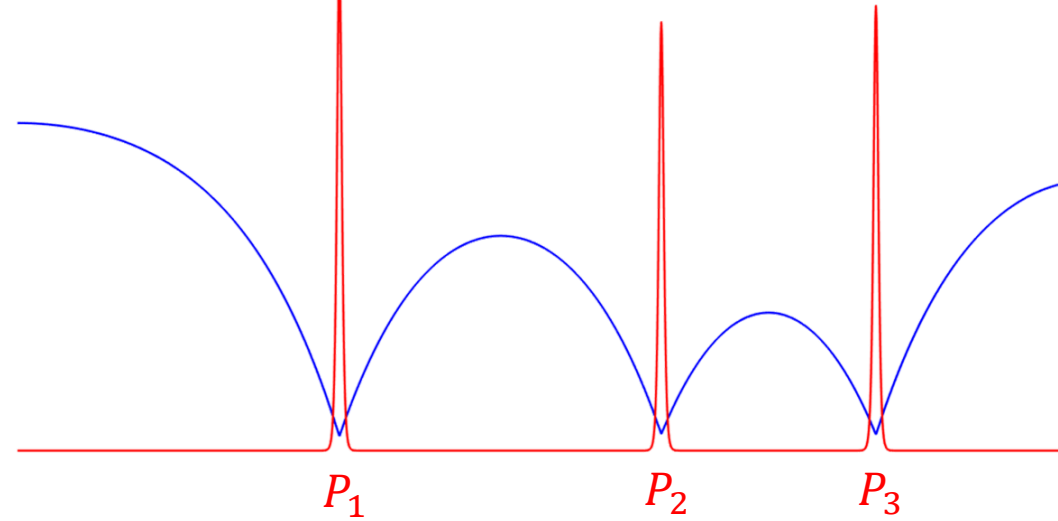
$$0 = w_{xx} + (h(\mathbf{x})_x w)_x - w + a(\mathbf{t})$$

Match solutions at boundaries:

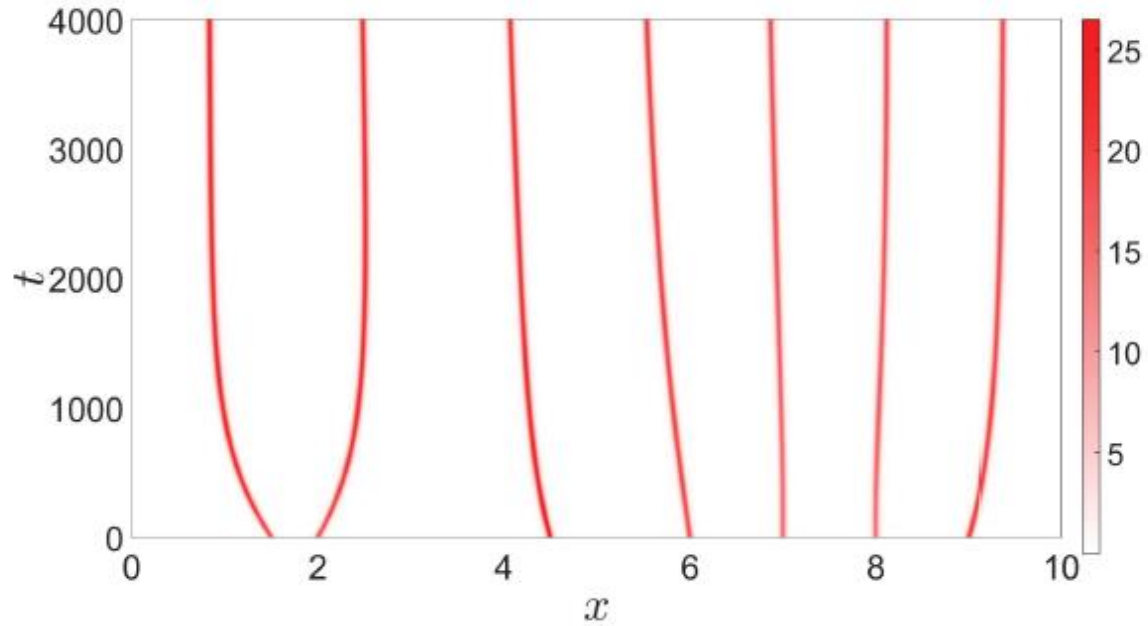
$$\rightarrow \frac{dP_j}{dt} = \frac{Da^2}{m\sqrt{m}} \left[w_x(P_j^+)^2 - w_x(P_j^-)^2 \right]$$

SLOW migratory movement of pulses

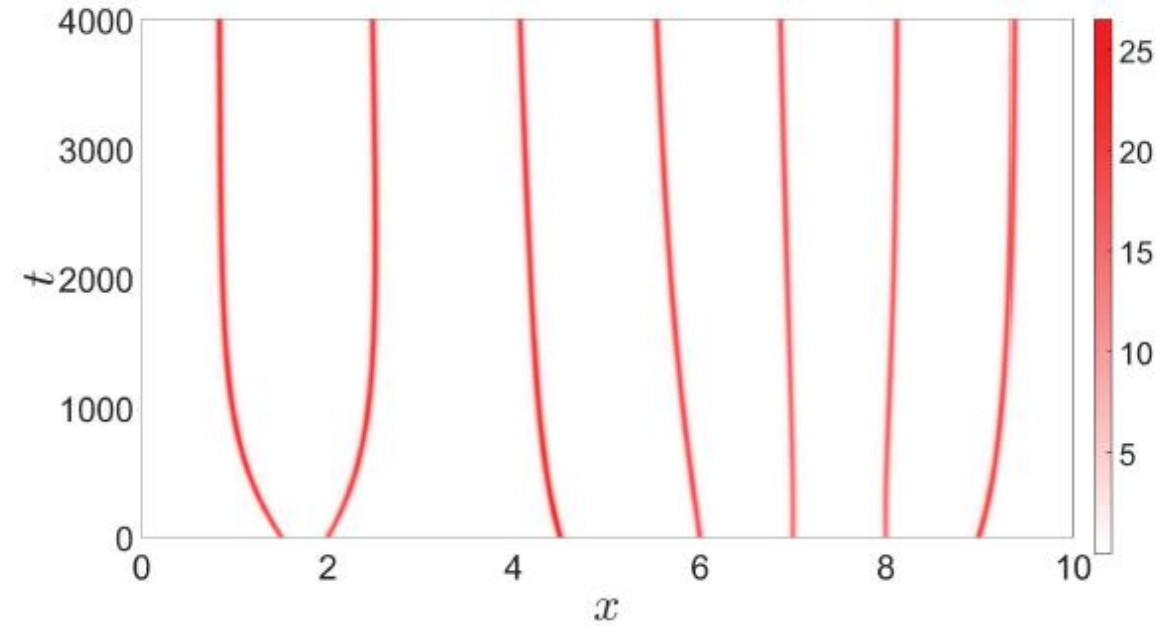
$$\frac{dP_j}{dt} = \frac{Da^2}{m\sqrt{m}} \left[w_x(P_j^+)^2 - w_x(P_j^-)^2 \right]$$



Comparison between full PDE and reduced ODE



(a) ODE



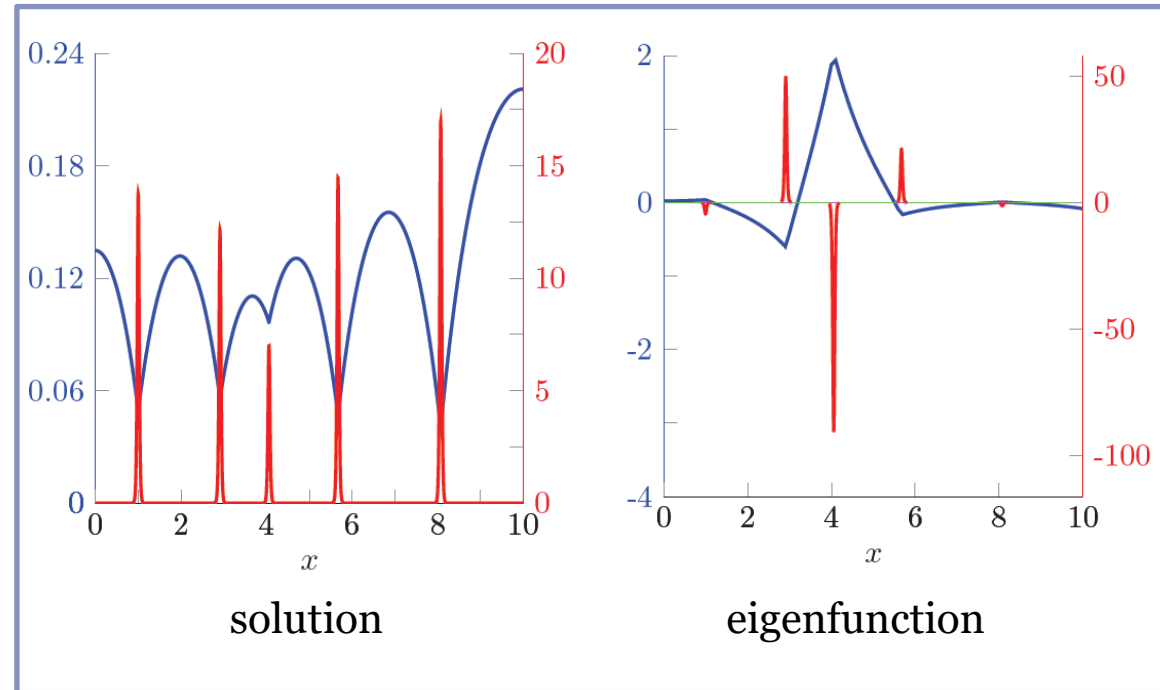
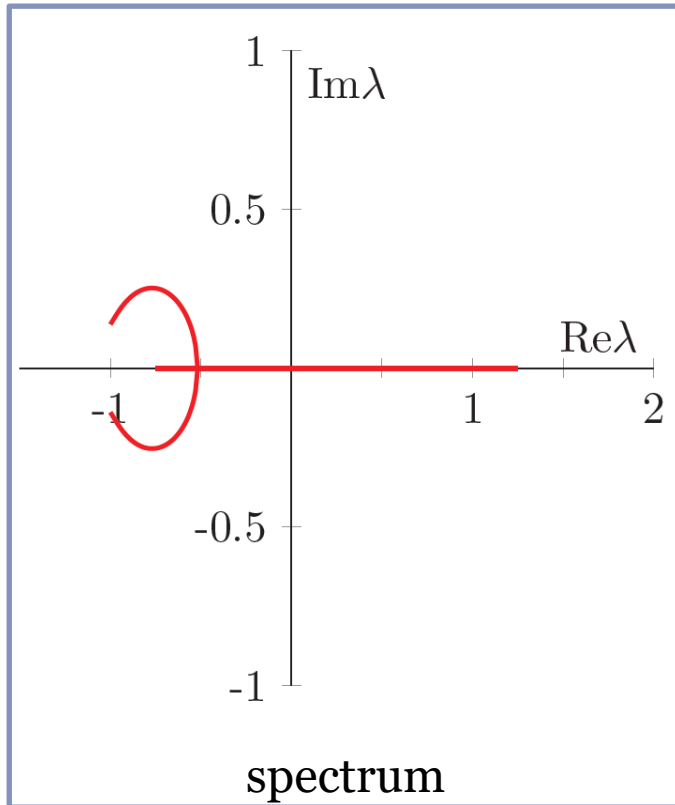
(b) PDE

2. Stability Criterium

Procedure:

Freeze solution in time

Study (quasi-steady) eigenvalues & eigenfunctions

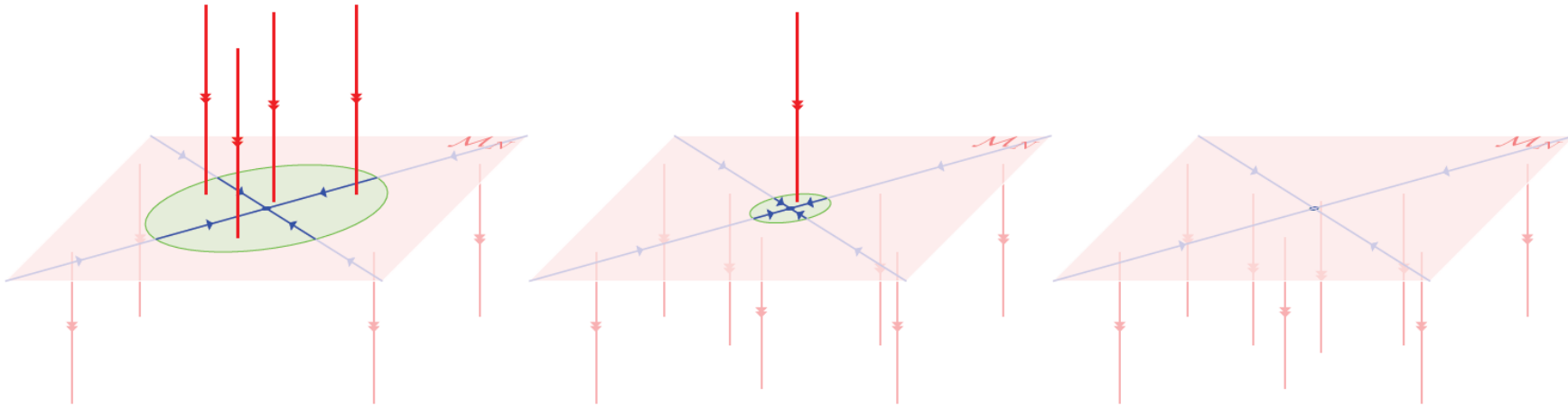


Nonlinear prediction based on linear analysis

2. Stability Criterion

Enough resources to sustain all vegetation patches?

Depends on **amount of rainfall** and **distance between pulses**



high rainfall

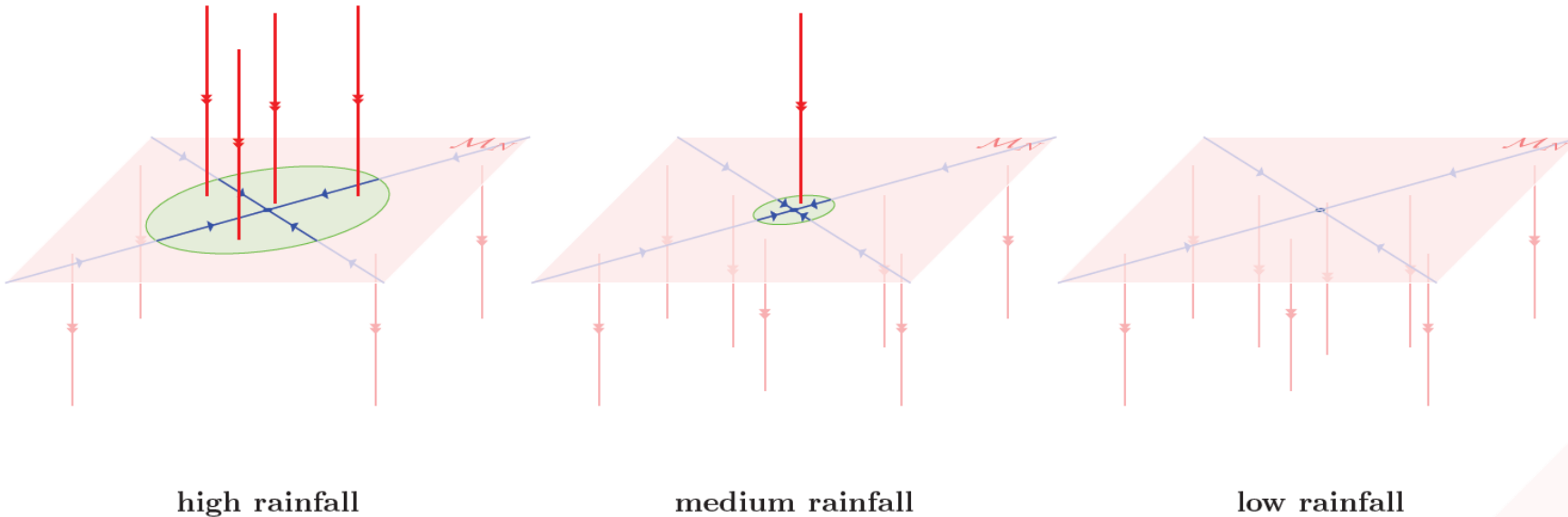
medium rainfall

low rainfall

2. Stability Criterium

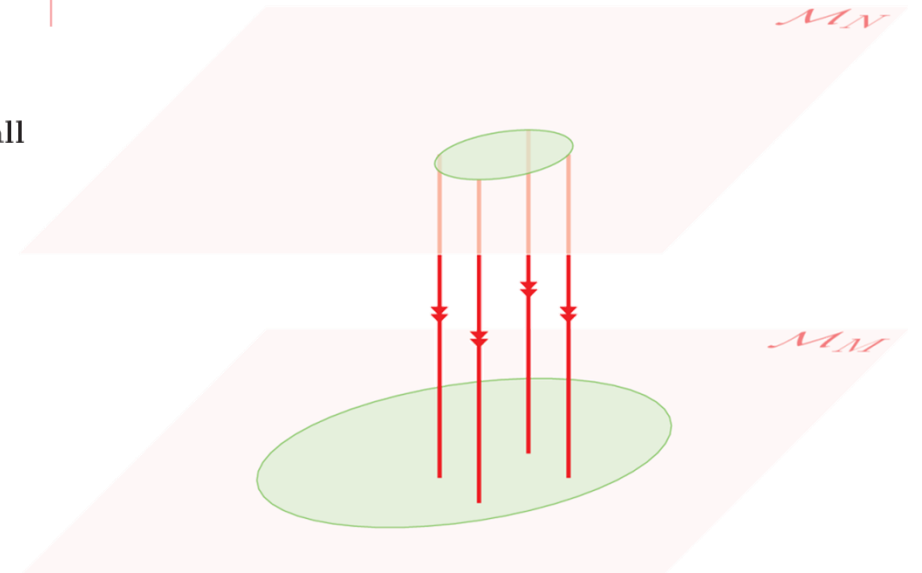
Enough resources to sustain all vegetation patches?

Depends on **amount of rainfall** and **distance between pulses**

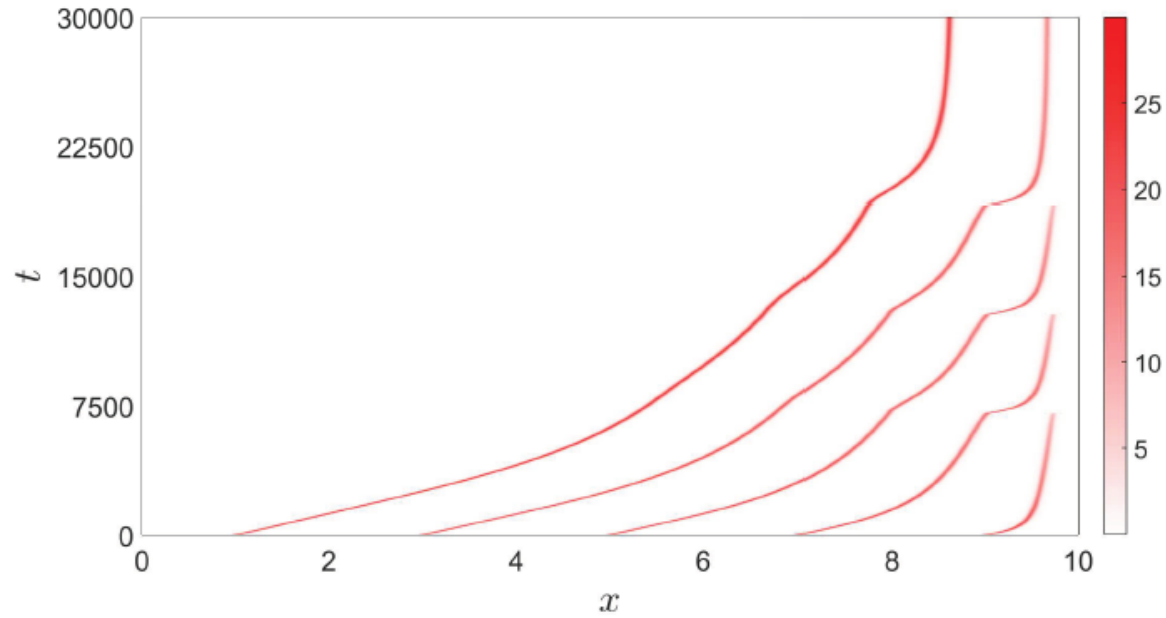


What happens when outside feasible region?

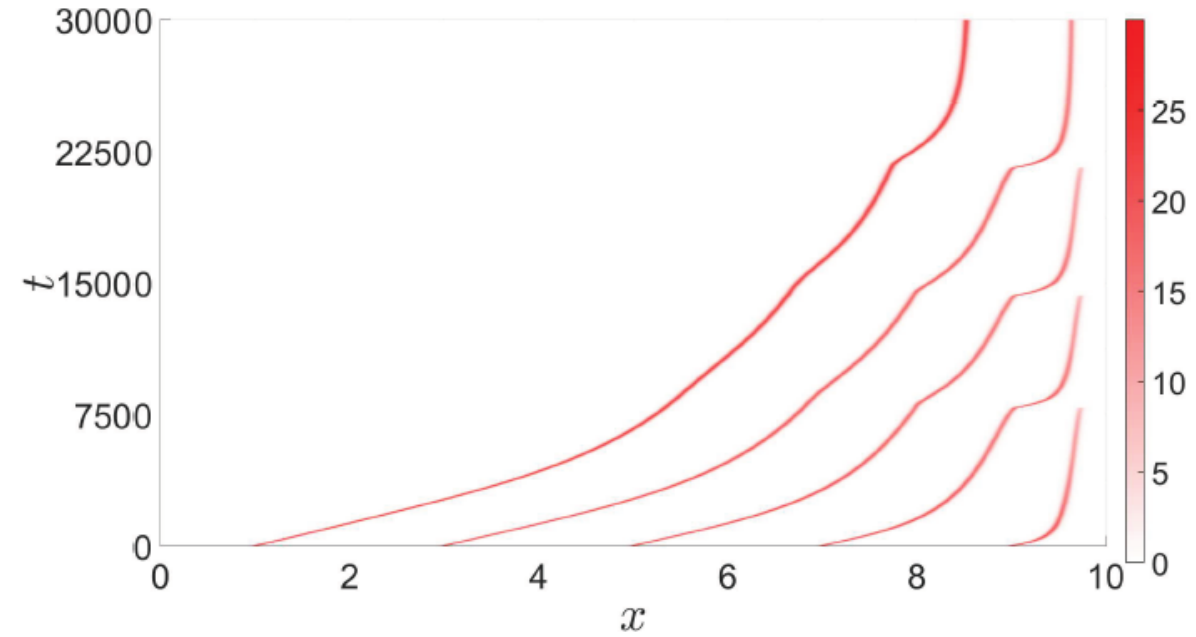
irregular configuration:	One patch disappears (least amount of biomass)
regular configuration:	Half of the patches disappears (wavelength doubling)



Comparison between full PDE and reduced ODE



(a) ODE



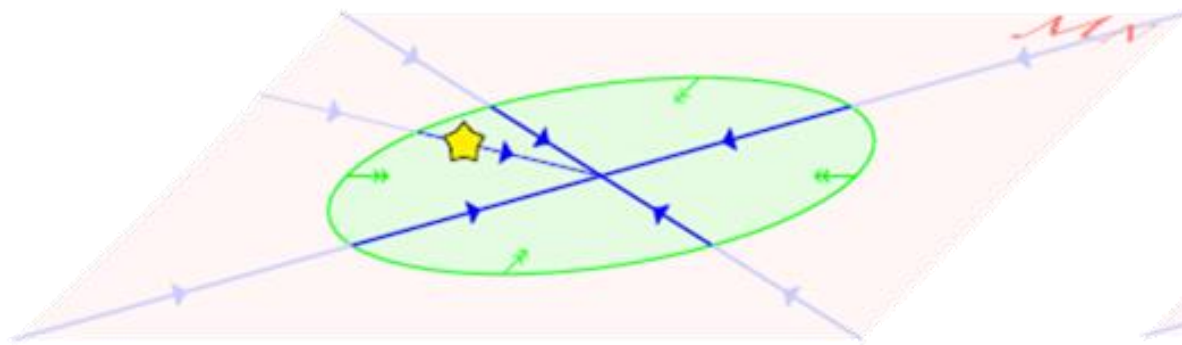
(b) PDE

Pulses during climate change (1)

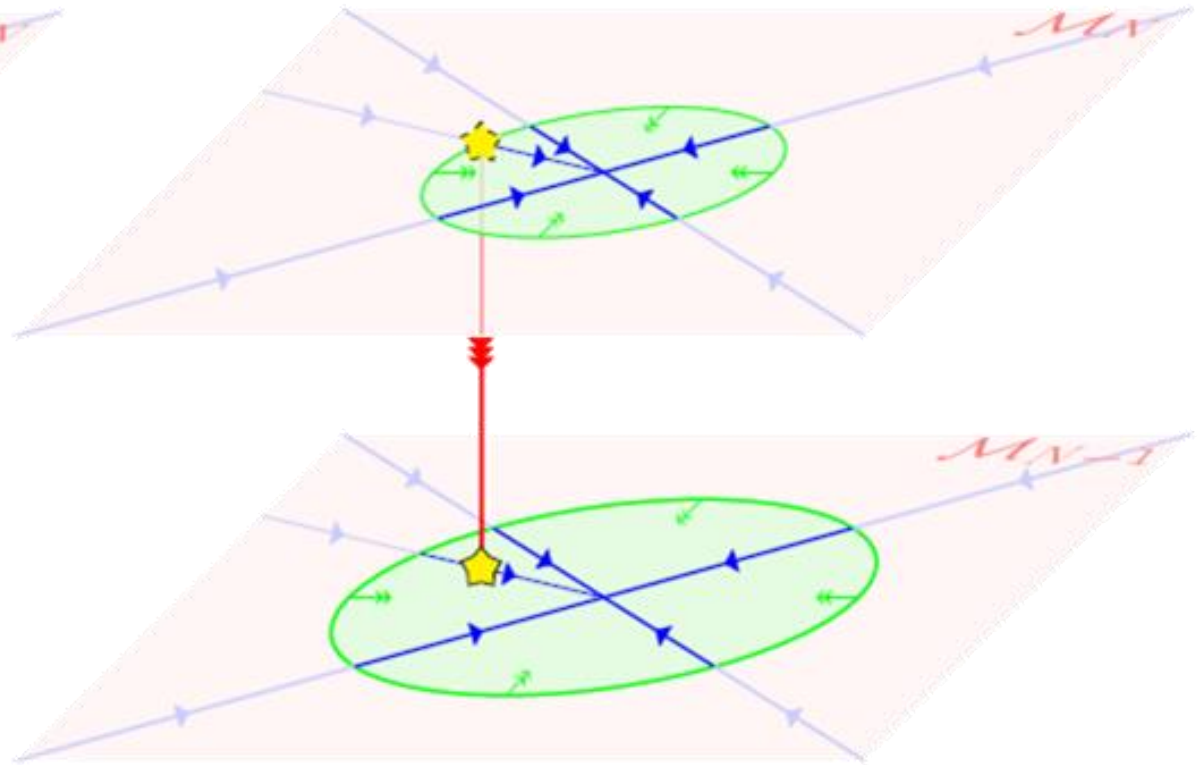
Competition of two effects:

1. Pulse rearrangement
2. Shrinking of feasible region

fast climate change



(a) initial configuration



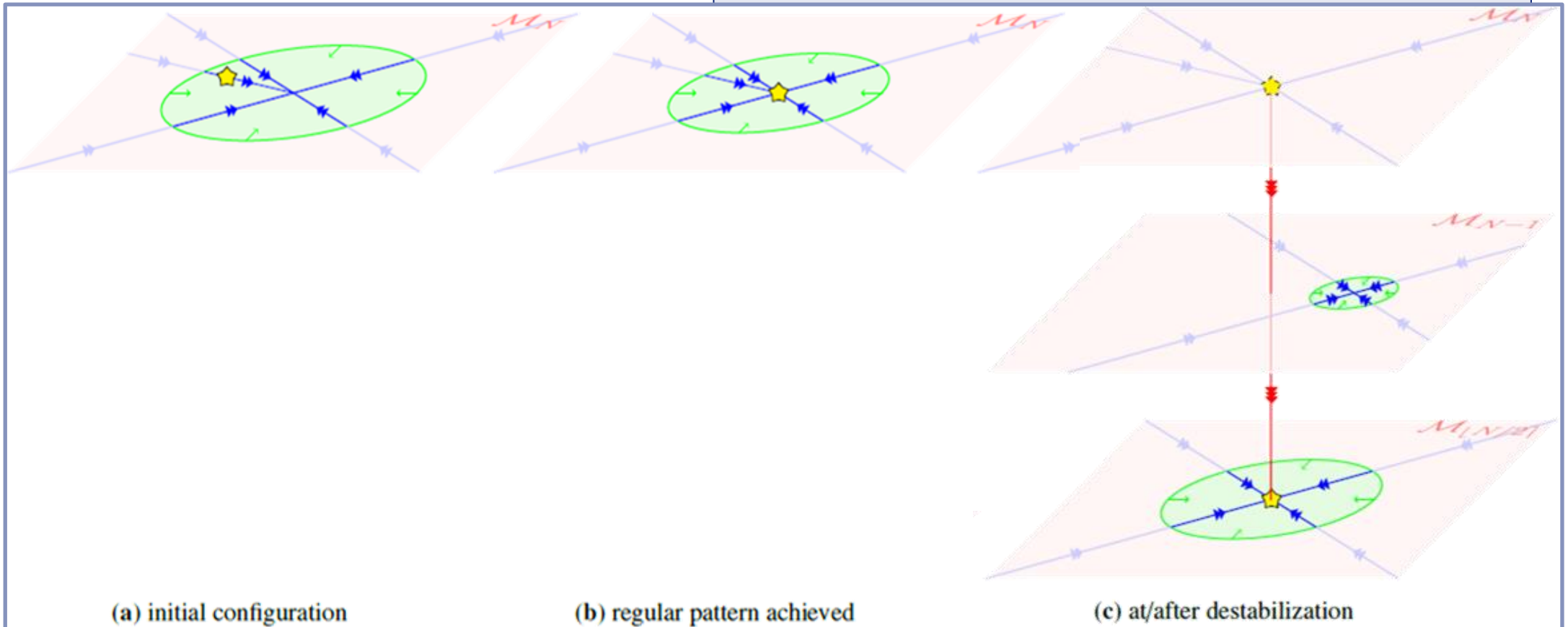
(b) at/after destabilization

Pulses during climate change (2)

Competition of two effects:

1. Pulse rearrangement
2. Shrinking of feasible region

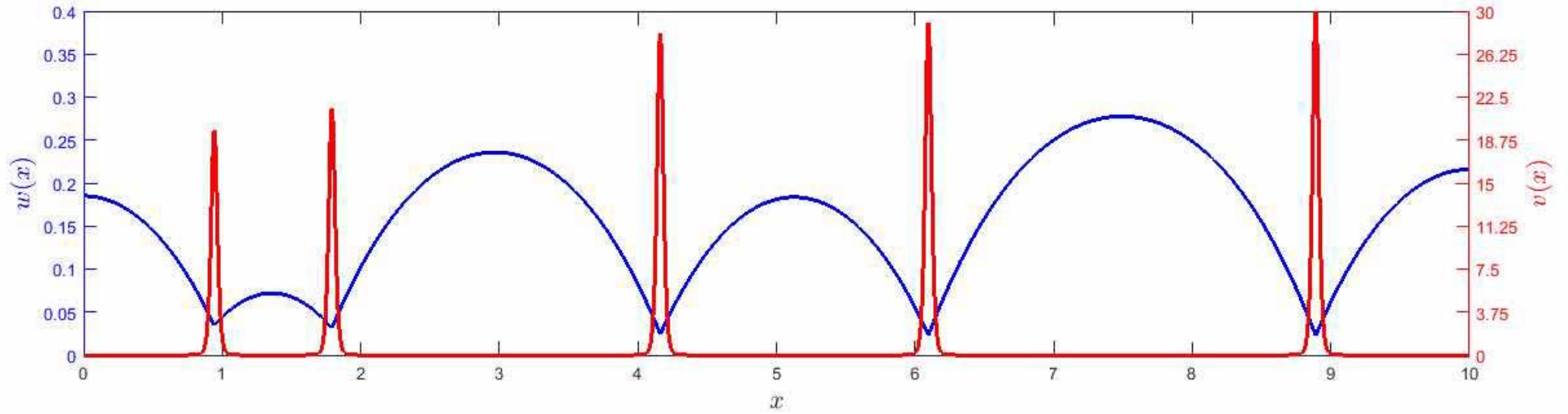
slow climate change



Pulses during climate change (3)

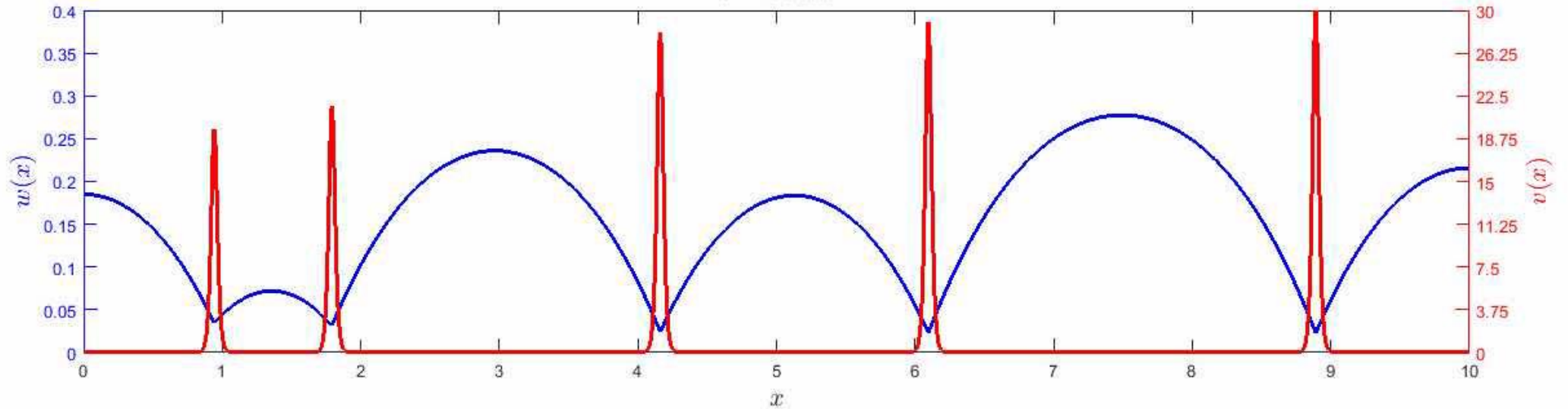
Rate of climate change

FAST



$a = 0.5000$

SLOW



An aerial photograph of a vast lavender field. The rows of purple lavender plants are neatly arranged in a grid pattern, separated by narrow dirt paths. A single, small green tree stands on a dirt road that runs diagonally across the field. The lighting is bright, casting soft shadows from the plants and the tree.

General Considerations

Stability of Stationary States

ODE

$$\lambda \bar{y} = f_y(y^*; \mu) \bar{y}$$

$Im \lambda$

×

×

×

×

×

$Re \lambda$

PDE

$$\lambda \bar{y} = \bar{y}_{xx} + f_y(y^*(x); \mu) \bar{y}$$

$Im \lambda$

×

×

×

×

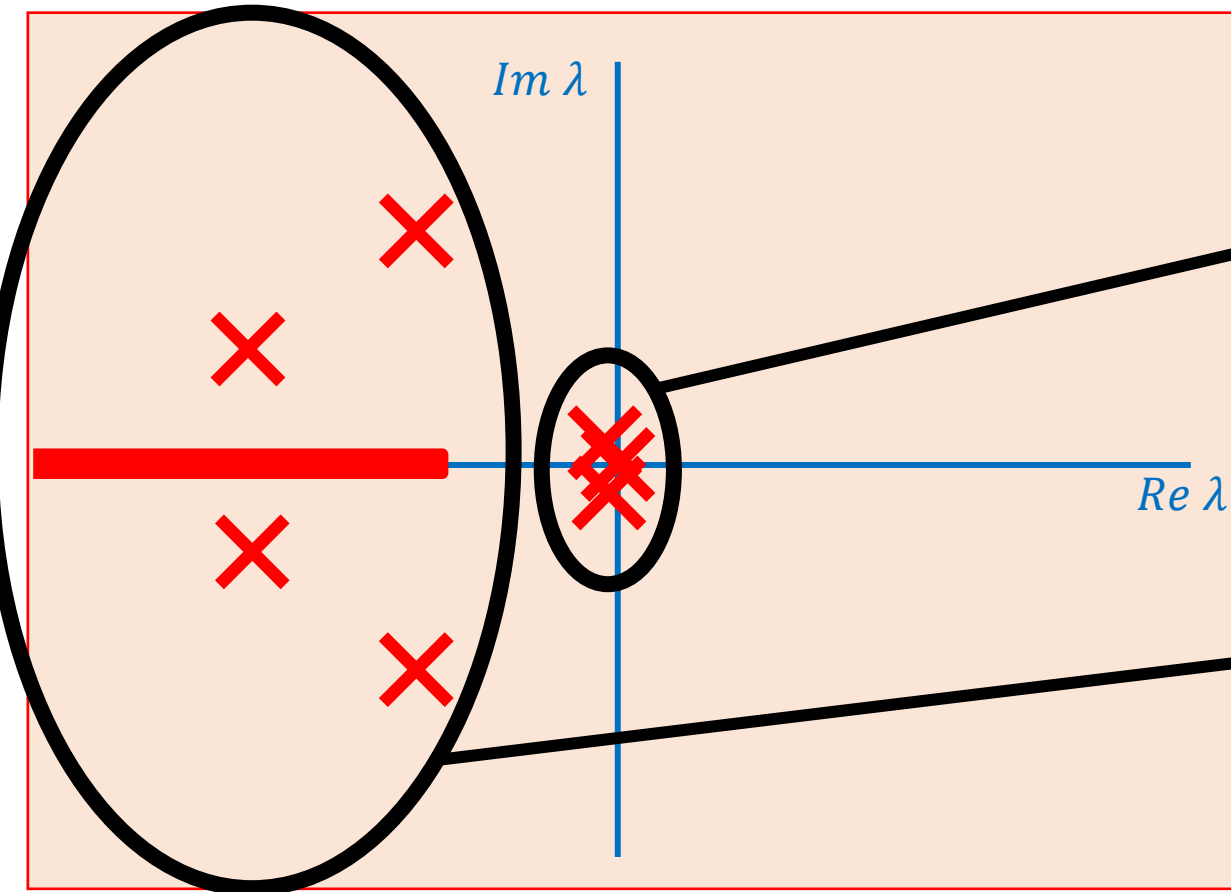
×

×

$Re \lambda$



Bifurcations



What happens at bifurcation?

1. SLOW Pattern Adaptation

At bifurcation:

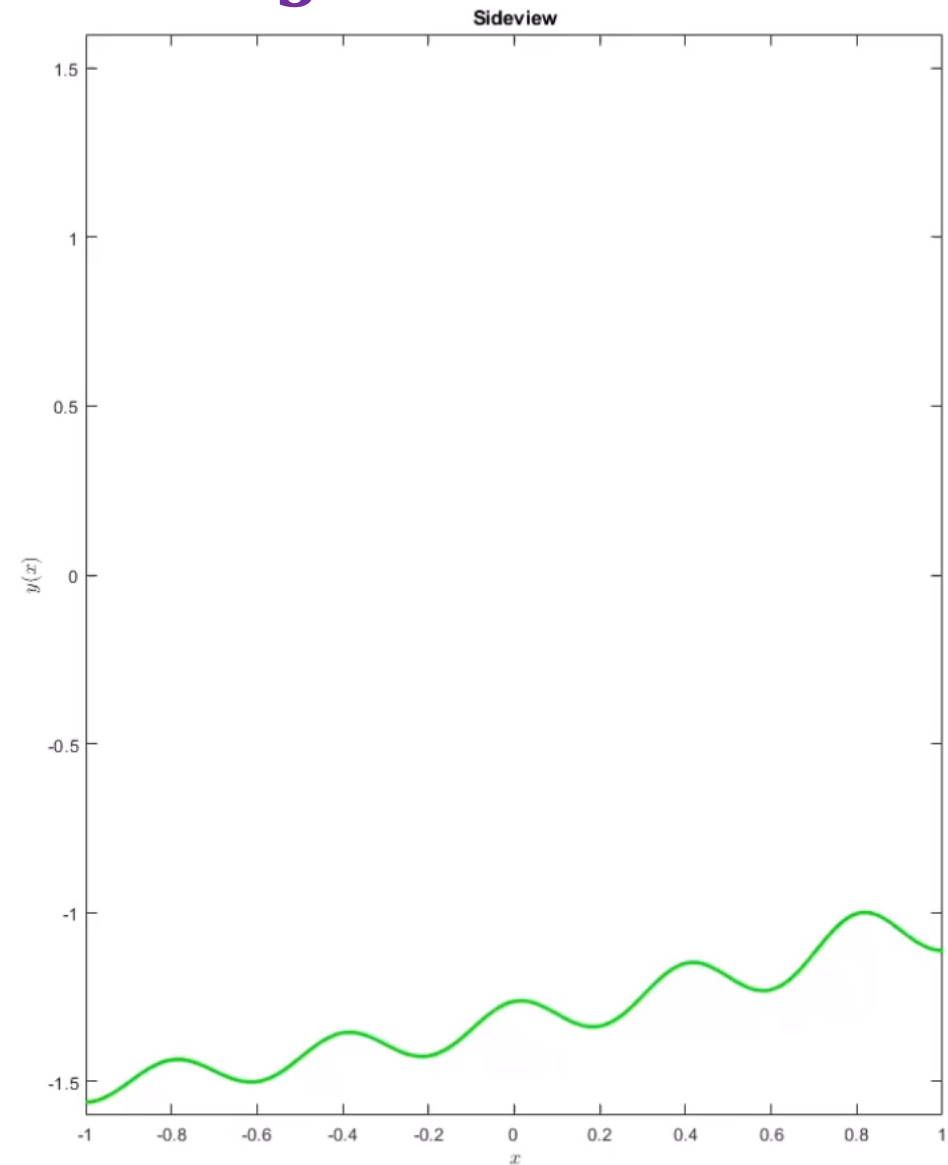
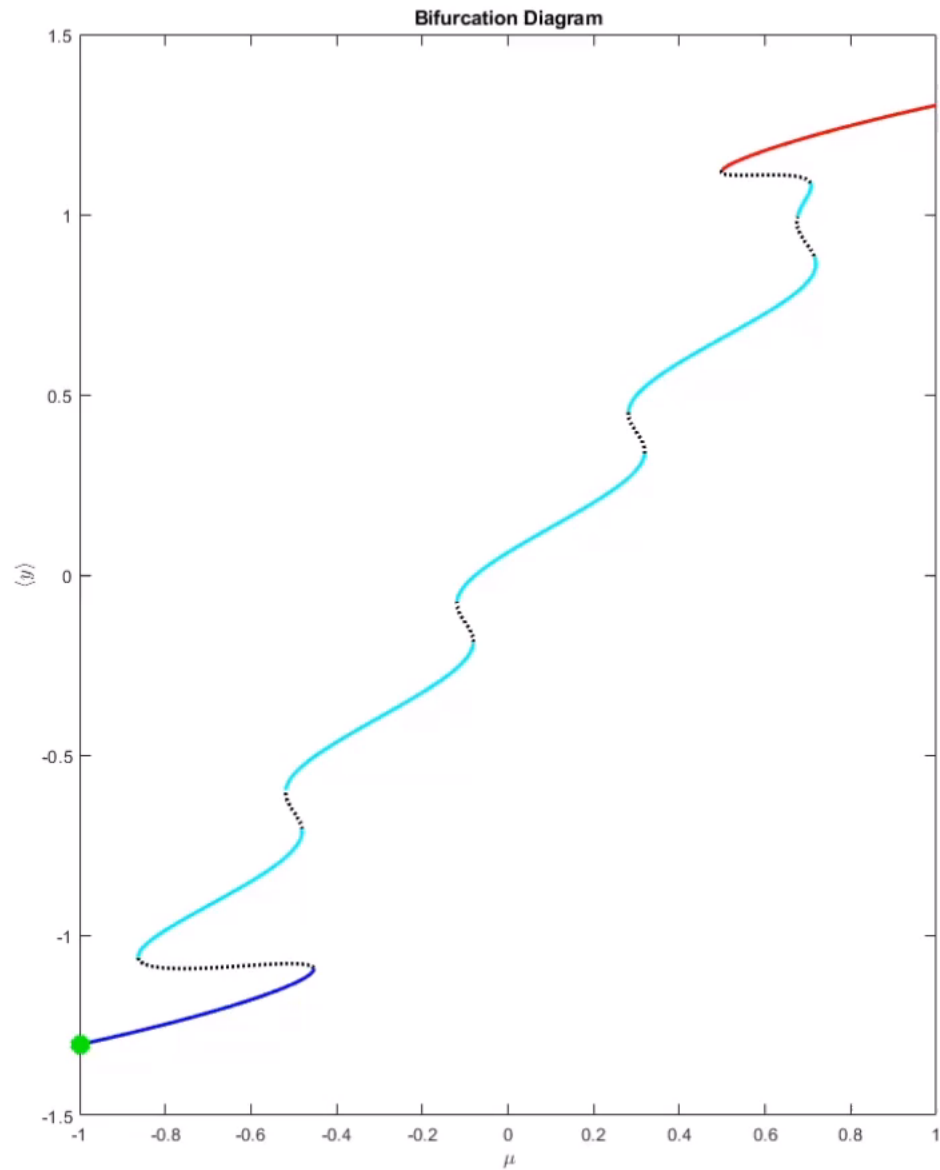
→ Location of structure changes

2. FAST Pattern Degradation

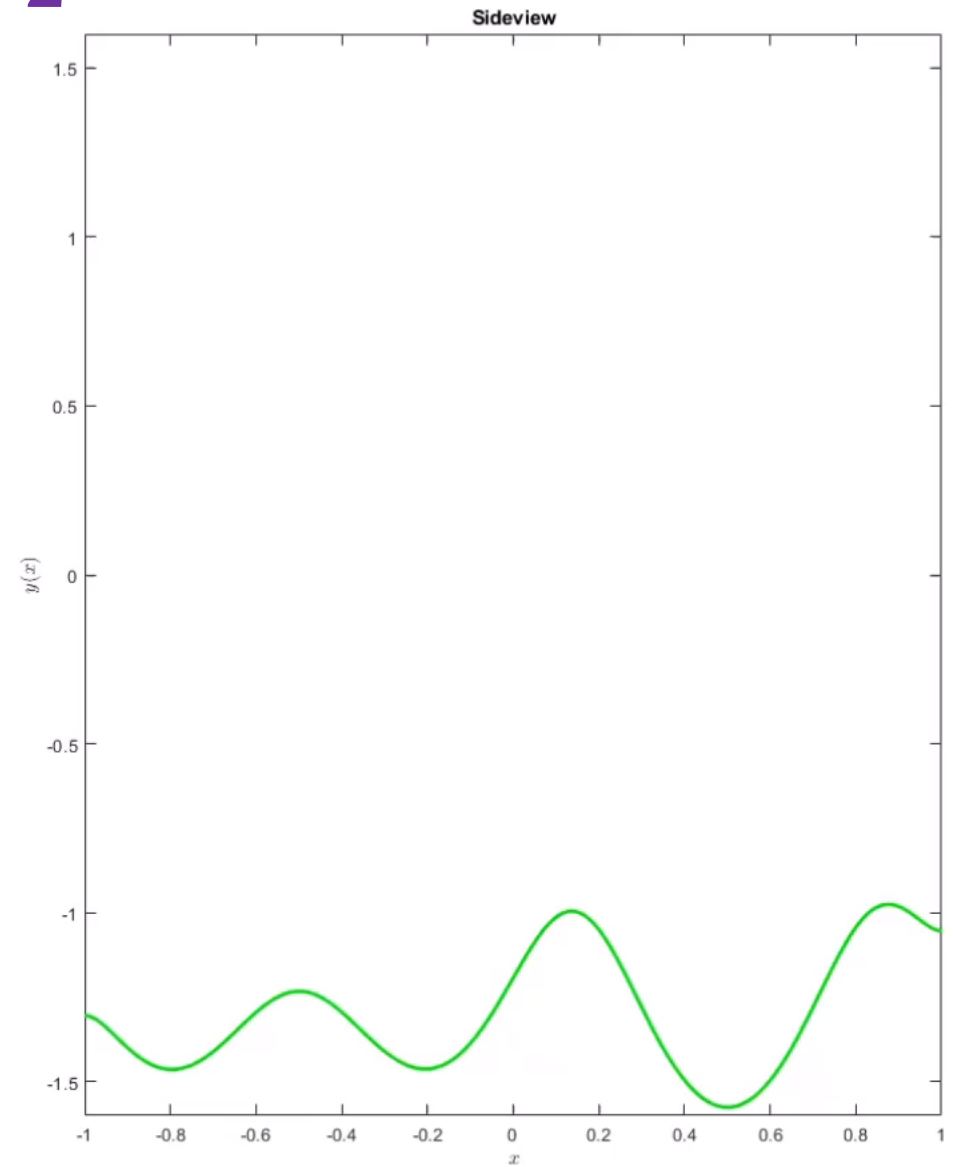
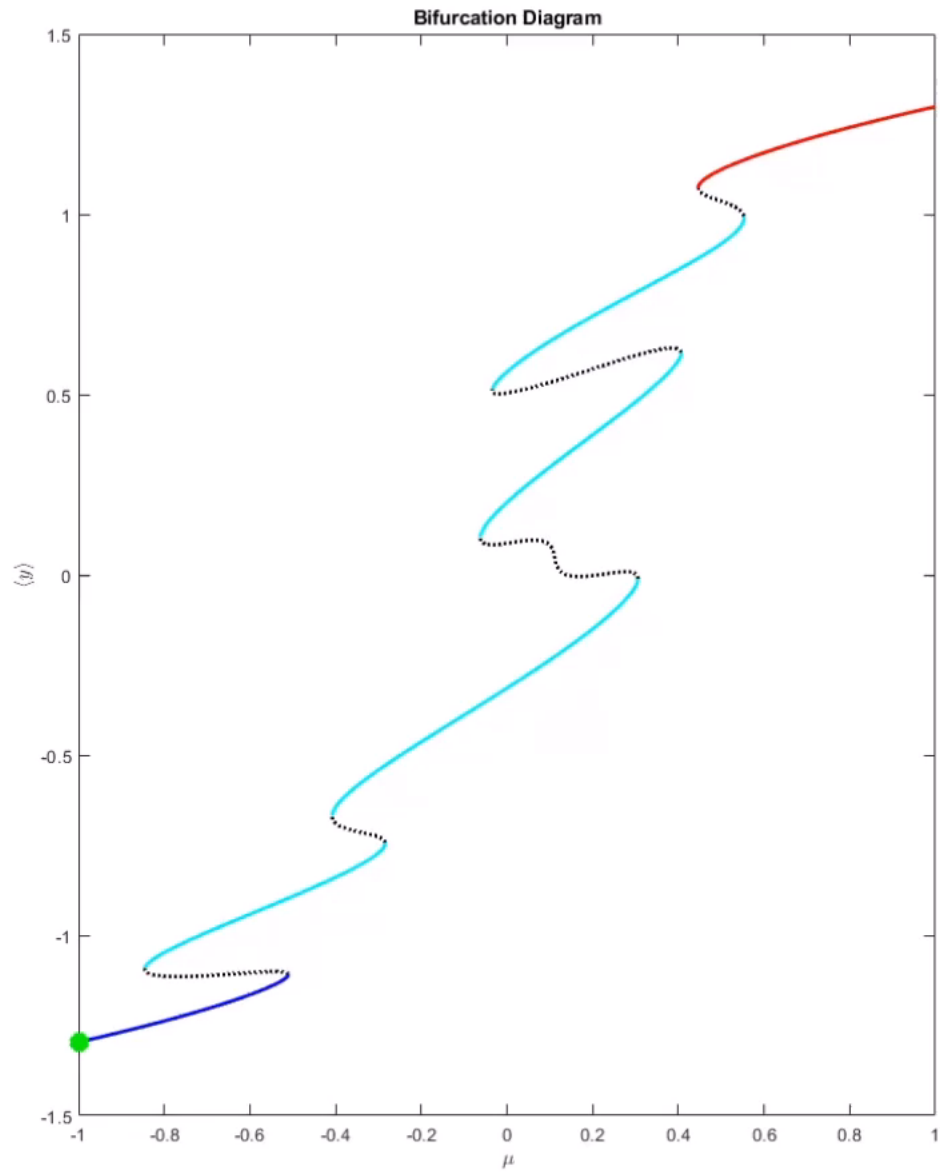
At bifurcation:

→ Structures created or destroyed

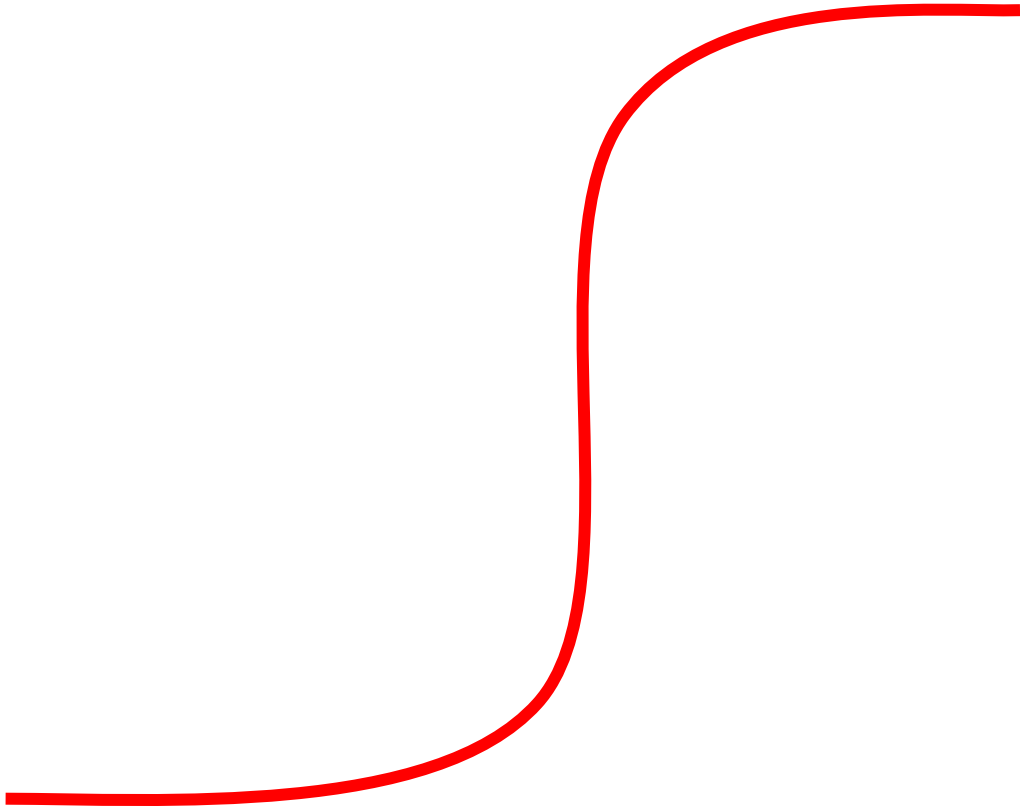
$$y_t = D y_{xx} + y(1 - y^2) + \mu + x + \frac{2}{5} \cos(5\pi x)$$



$$y_t = D y_{xx} + y(1 - y^2) + \mu + \frac{1}{2} \cos(2\pi x) + \sin(3\pi x)$$



Destabilizations in 2D



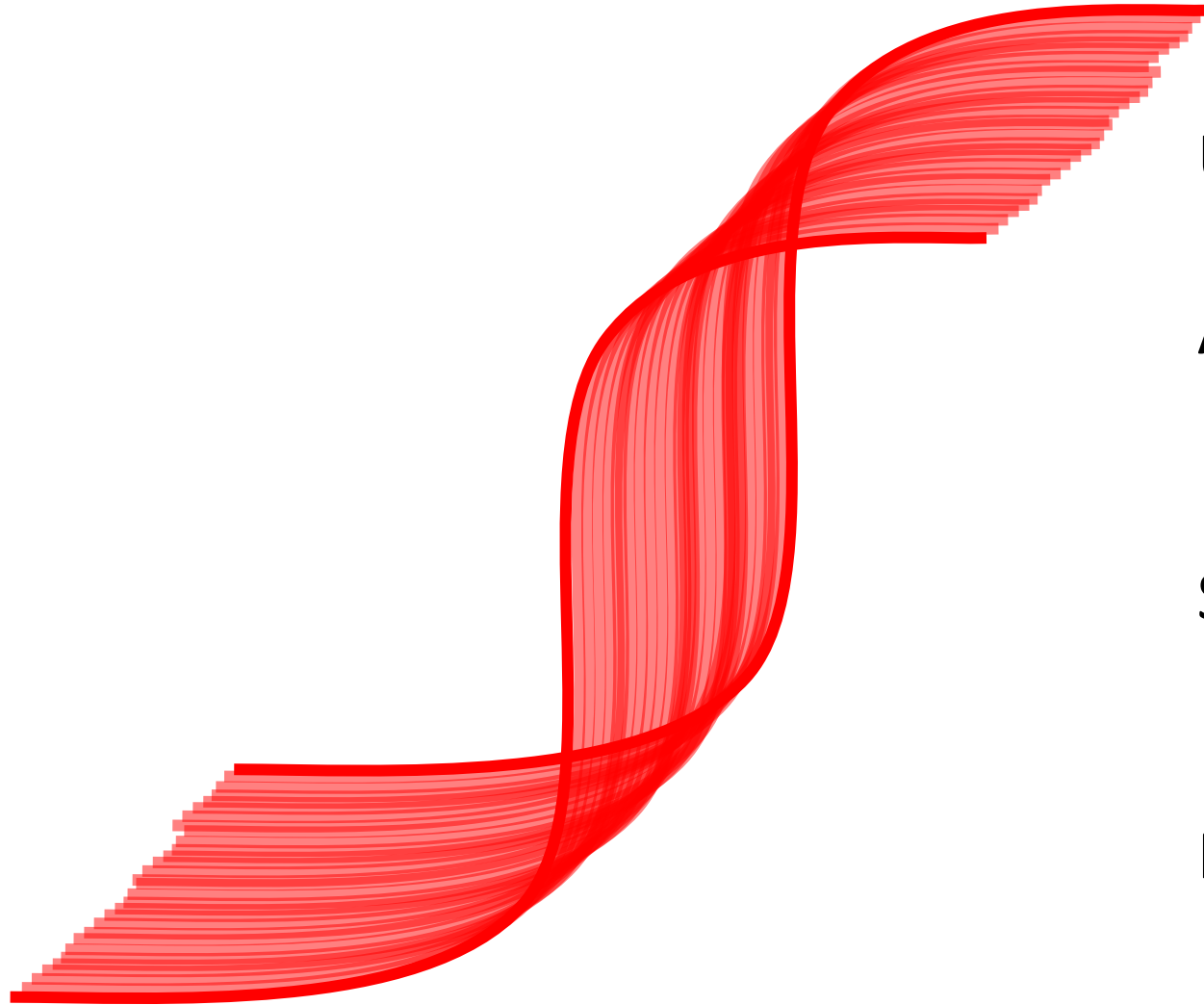
Until now

$$u_t = u_{xx} + F(u)$$

Adding another spatial dimension:

$$u_t = u_{xx} + u_{yy} + F(u)$$

Destabilizations in 2D



Until now

$$u_t = u_{xx} + F(u)$$

Adding another spatial dimension:

$$u_t = u_{xx} + u_{yy} + F(u)$$

Solution in 2D:

$$u^*(x, y) = u_{1D}^*(x)$$

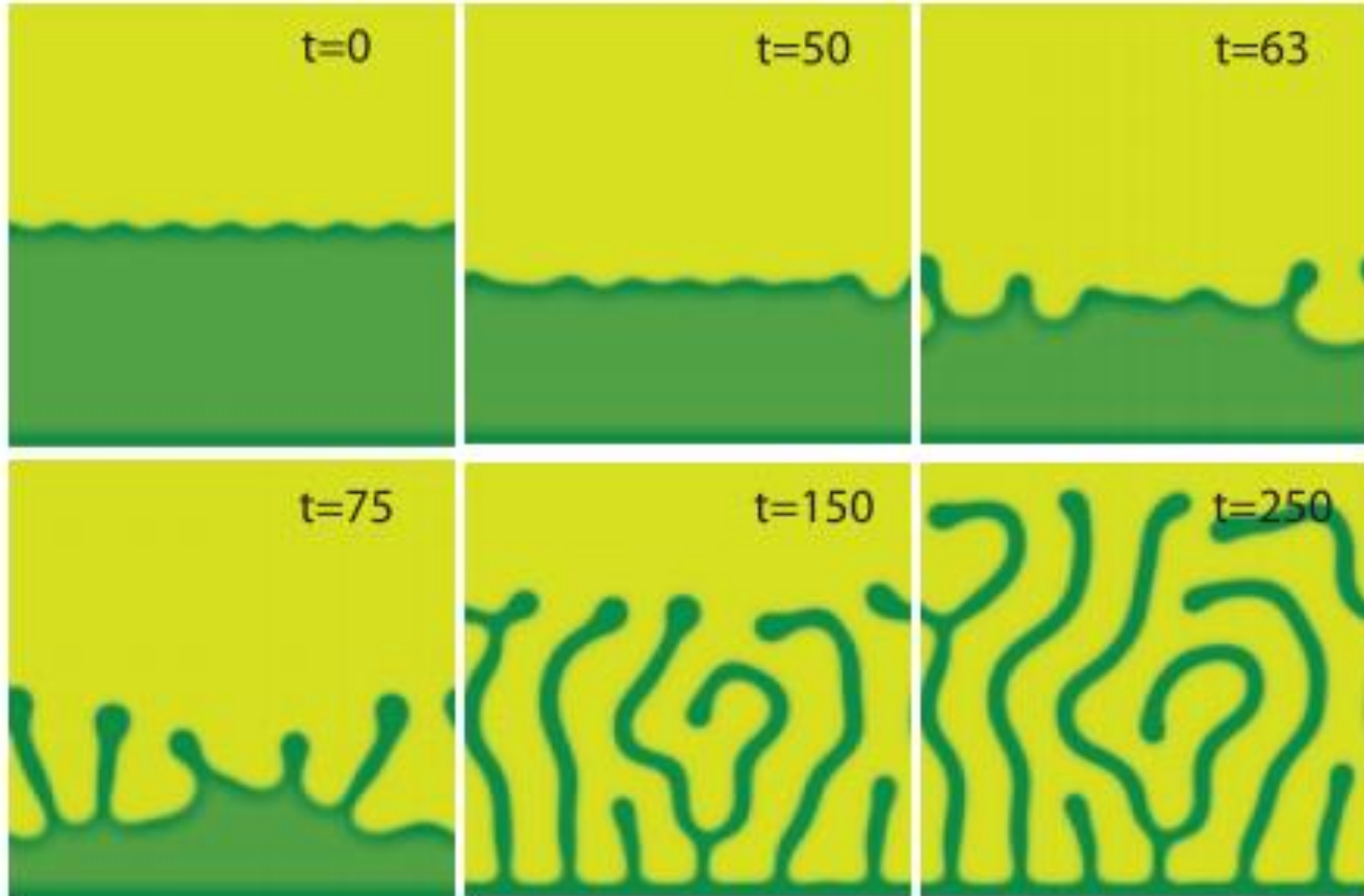
For stability analysis, use

$$u(x, y) = u_{1D}^*(x) + e^{iky} e^{\lambda t} \bar{u}(x)$$

to get:

$$\lambda \bar{u} = (\partial_x^2 - k^2) \bar{u} - F_u(u^*) \bar{u}$$

Fingering instability



Summary – Dynamics of existing patterns

Dynamics of patterned states is a combination of:

1. SLOW Pattern Adaptation

At bifurcation:

→ Location of structure changes

&

2. FAST Pattern Degradation

At bifurcation:

→ Structures created or destroyed

Slides available at:
[bastiaansen.github.io/
MTpatterns/patternMT
.html](https://bastiaansen.github.io/MTpatterns/patternMT.html)

